

# Flash-Flood Frühwarnung

via

Expanded Downscaling von Ensemble-Vorhersagen

*G. Bürger, D. Reusser, D. Kneis*

- Ensembles
- Expanded Downscaling
- Verifikation
- Deterministisch oder probabilistisch?
- Nutzer und das cost-loss Modell
- Warnung wie früh?

# Methodik

- **Idee:** Klima-downscaling für Wettervorhersage
- **Methode:**
  - Ensemble Prediction System (EPS) des ECMWF
  - Expanded Downscaling (EDS)
  - EPS → EDS → Niederschlagsensembles für OPAQUE (Alb, Donau)
  - Verifikation, tägl. 2002-2005 (deterministisch, probabilistisch)
  - Vergleich mit LM
- **Ziel (Resultat?):** Frühwarnung (3-5 Tage)

# Ensemble prediction: A pedagogical perspective

Tim Palmer, Roberto Buizza, Renate Hagedorn, Andy Lawrence, Martin Leutbecher, Lenny Smith

The ECMWF Ensemble Prediction System (EPS) has featured extensively in the ECMWF Newsletter, including articles assessing the performance of the EPS, planned for EPS, the EPS in No. 104, reviewed EPS in f by Mark Rodwell.

Despite the fact that the EPS brings additional value to ECWMF's dissemination products through its ability to assess flow-dependent weather risk, the EPS is a less straightforward

tool to use than the more traditional deterministic forecast. Not surprisingly, therefore, conceptual questions are sometimes asked about the EPS. Here are some examples. What is the relationship between the spread and skill within the EPS? If the northern hemisphere RMS error of a typical ensemble member is routinely larger than that of the corresponding

Ensemble **Breite** als Maß für die **Unsicherheit** des Ensemble-Mittels

are better than the deterministic forecast locally, compared with hemispherically? Are the baroclinically-tilted structures often seen in the EPS initial perturbations consistent with our knowledge of analysis error? Perhaps most important of all

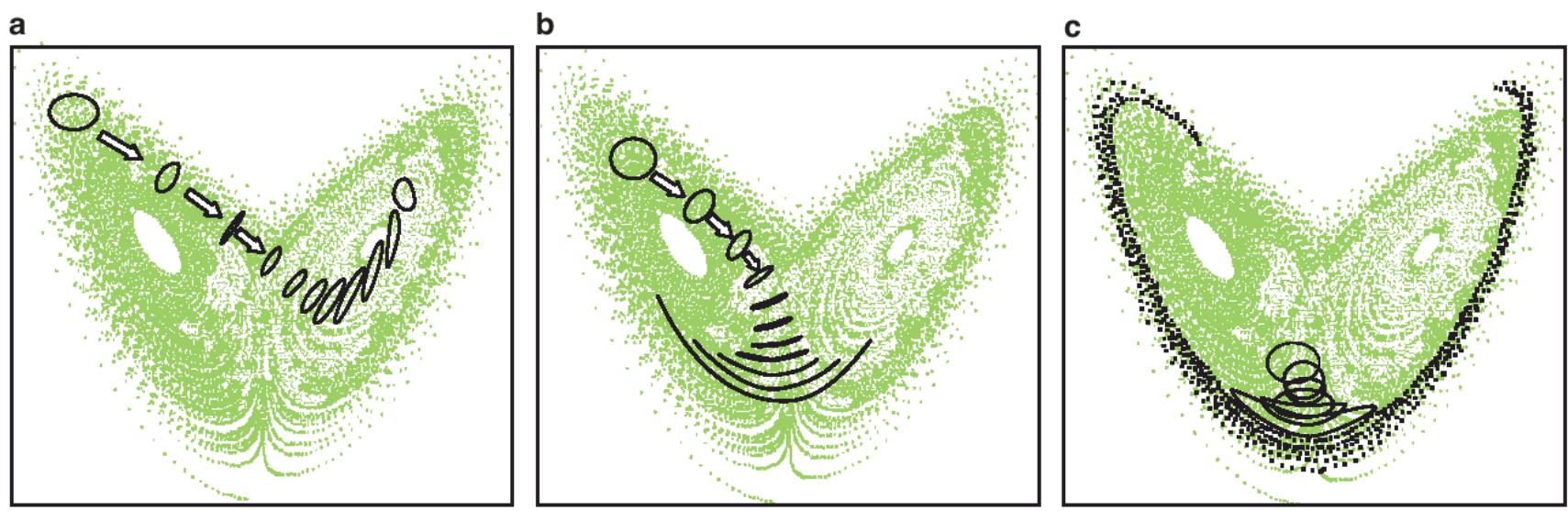
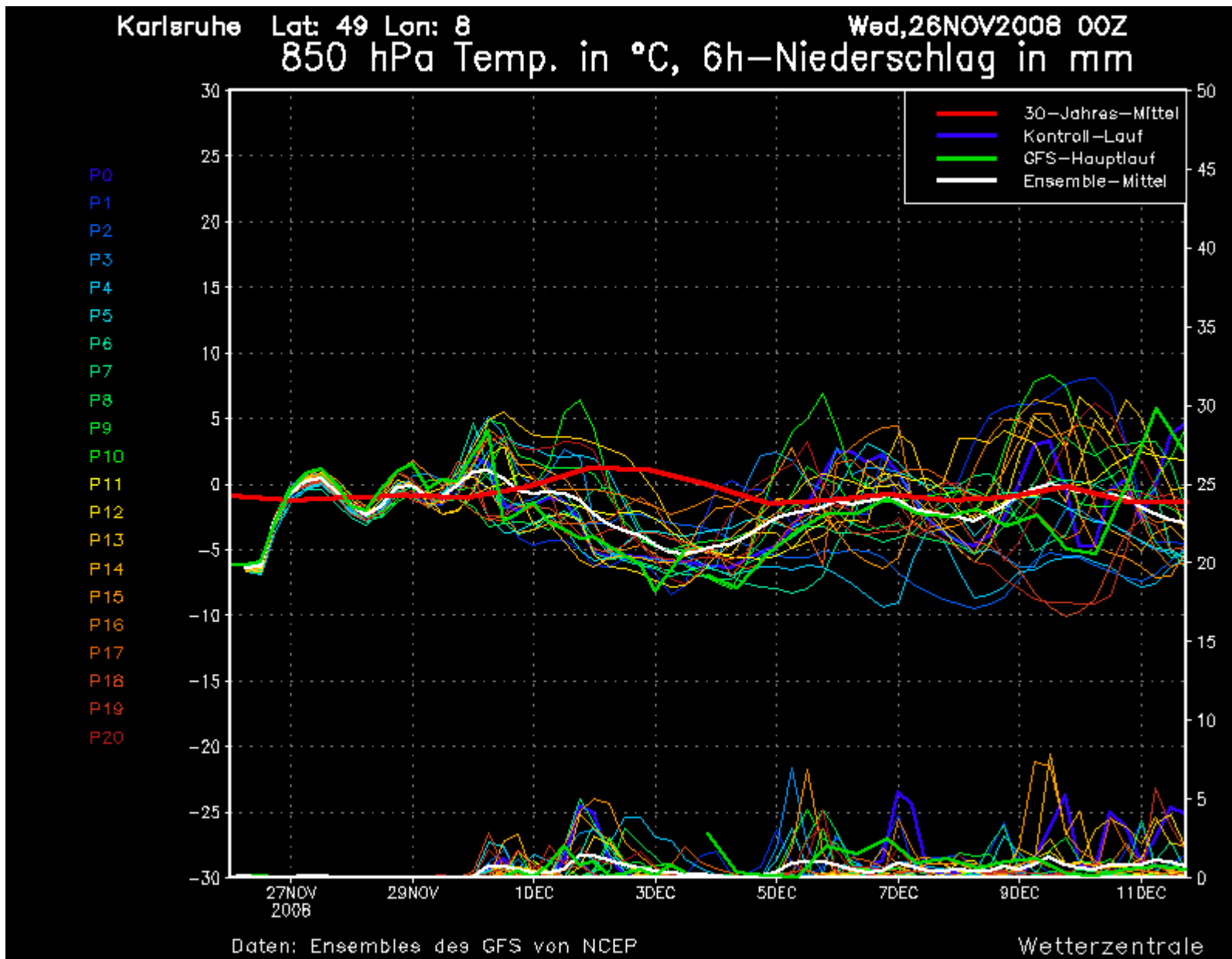



Figure 1 Scientific basis for ensemble forecasting. In a nonlinear system the growth of initial uncertainty is flow dependent – here illustrated with the Lorenz (1963) model. The set of initial conditions (black circle) is located in different regions of the attractor in (a), (b) and (c).



# ECMWF

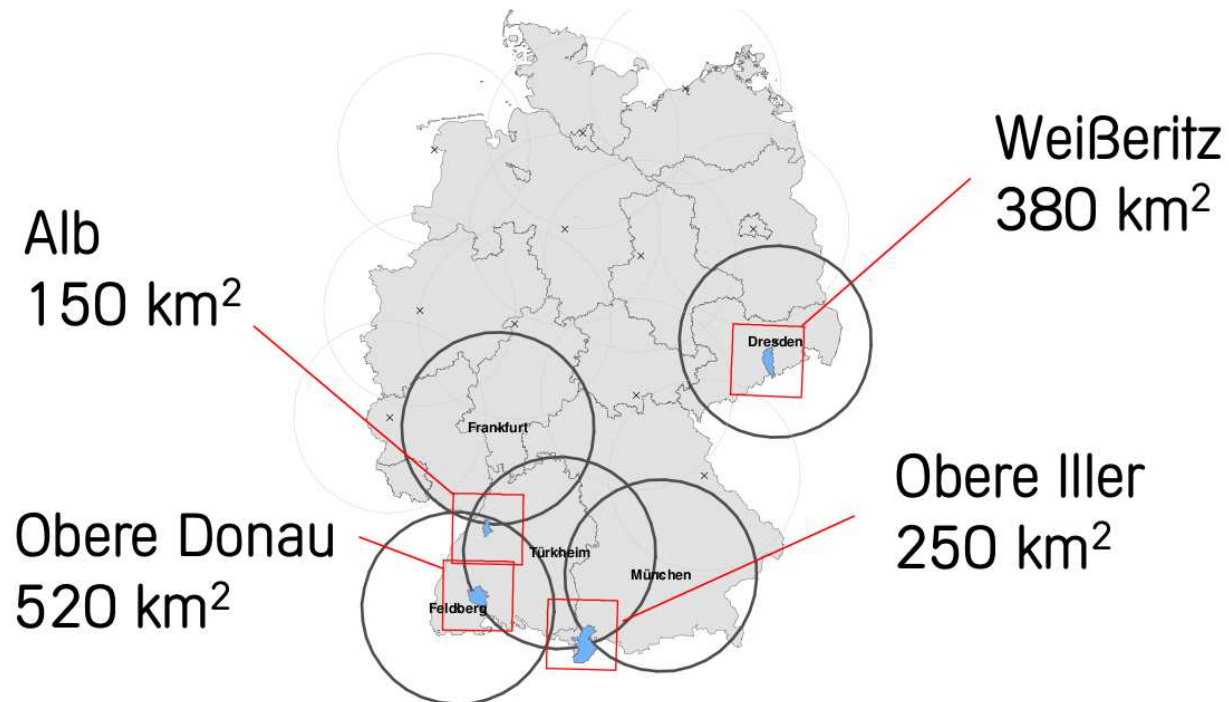
**Current operational status:**

- **4D-var analysis:** T159(120km) 12h minimisation, twice per day (03-15UTC, 15-03 UTC)
- **Deterministic forecast:**
  - T511L60 (40km), 240h, one per day (12UTC)
  - Oceanic waves: 55km grid, T30, 24 directions
- **Limited Area Oceanic Waves** (European Waters) 28km grid
- **EPS:**
  - Initial perturbations: T42L31(500km)
  - 50+1 forecasts T255L40 (80km), 240h, 1 per day (12UTC)
  - Oceanic waves: 110 km grid, 25 directions, 12 directions

Medium-Range Forecasts Users Meeting (Reading, 17-18 June 2002) 4 **ECMWF** 

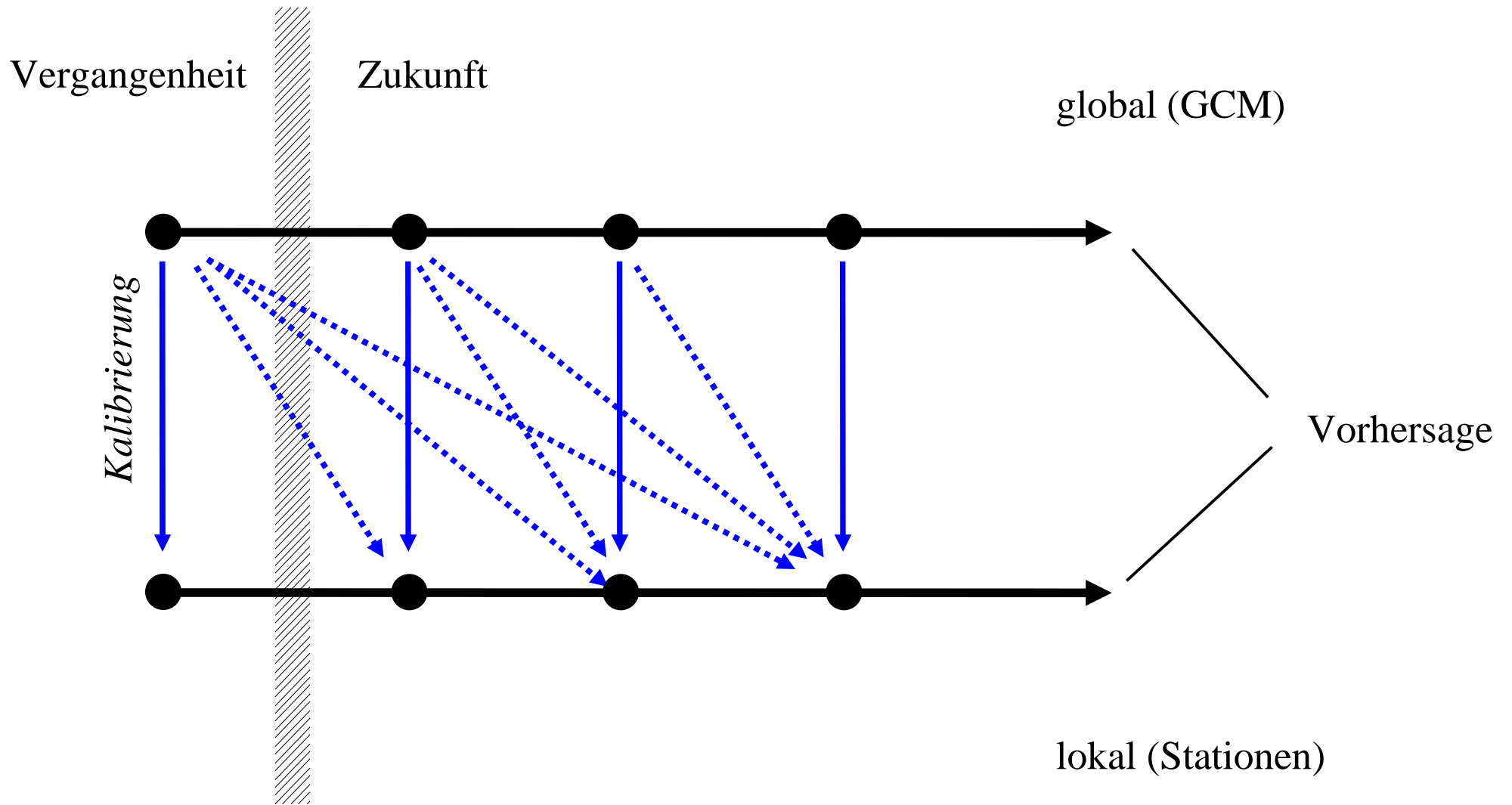
## Untersuchungsgebiete

### HW-Vorhersage in kleinen Mittelgebirgseinzugsgebieten



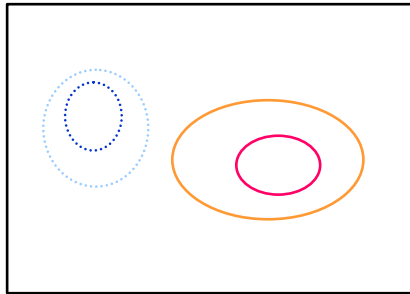
Operationelle Abfluss- und Hochwasser-Vorhersage in Quellgebieten – OPAQUE

# „perfect prog(nosis)“



# Expanded downscaling (EDS)

globale Zirkulation  $\xi$

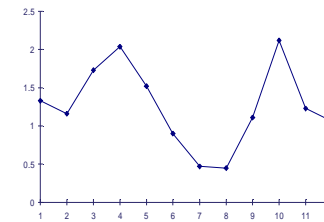


Transferfunktion  $f$

$$\eta = f(\xi) + \text{"Fehler"}$$



lokales Wetter  $\eta$



- minimiere "Fehler"  $\rightarrow f =$  multiple lineare Regression
- minimiere "Fehler" **und** erhalte lokale Kovarianz  $\rightarrow f =$  expanded downscaling
- Resultat: größerer Fehler, aber **realistische Kovariabilität**



## Ein bißchen Mathematik ... Lösungsmatrix für EDS

$$f = E = G_{\xi}^{-1} V U' G_{\eta}$$

$G_{\xi}$  und  $G_{\eta}$  die Cholesky-Faktoren von  $\xi'\xi$  und  $\eta'\eta$ ,

$U$  and  $V$  aus der SVD:

$$U \Sigma V' = G_{\eta} \eta' \xi G_{\xi}^{-1}$$

## Atmosphärische Felder ( $\xi$ ) für EDS

- at 850hPa
  - $z$ , geopotential height
  - $vo$ , vorticity
  - $t$ , temperature
  - $q$ , specific humidity
- at sfc
  - $tp$ , total precipitation
- ~100 dominante EOFs, von  $825 = 5 \times (15 \times 11)$  Gitterpunkten

Deutschland

EDS kein MOS

## Numerik

$$\boxed{\eta} = \boxed{\mathbf{E}} \times \boxed{\xi}$$

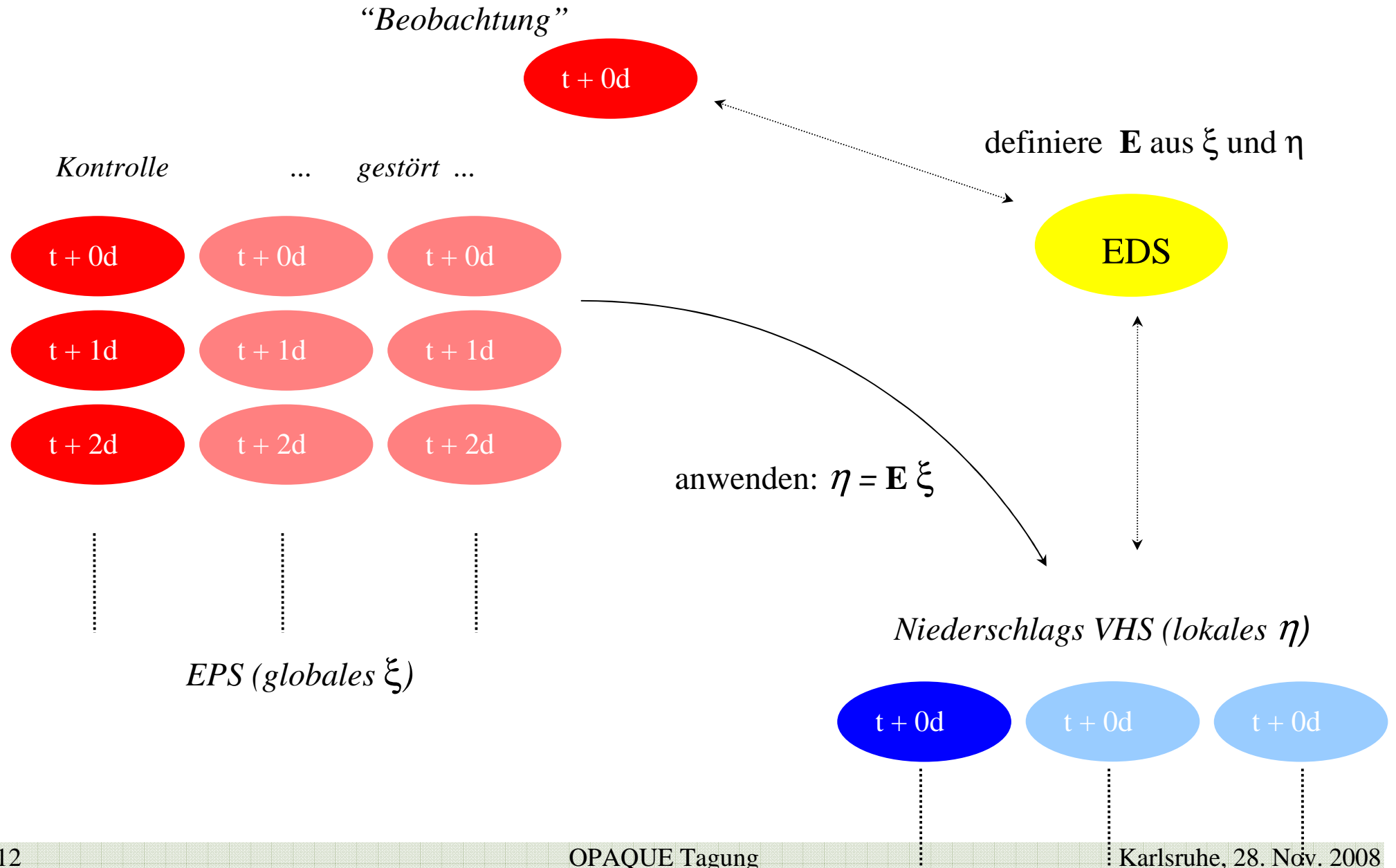
lokaler Niederschlag

ECMWF-Felder

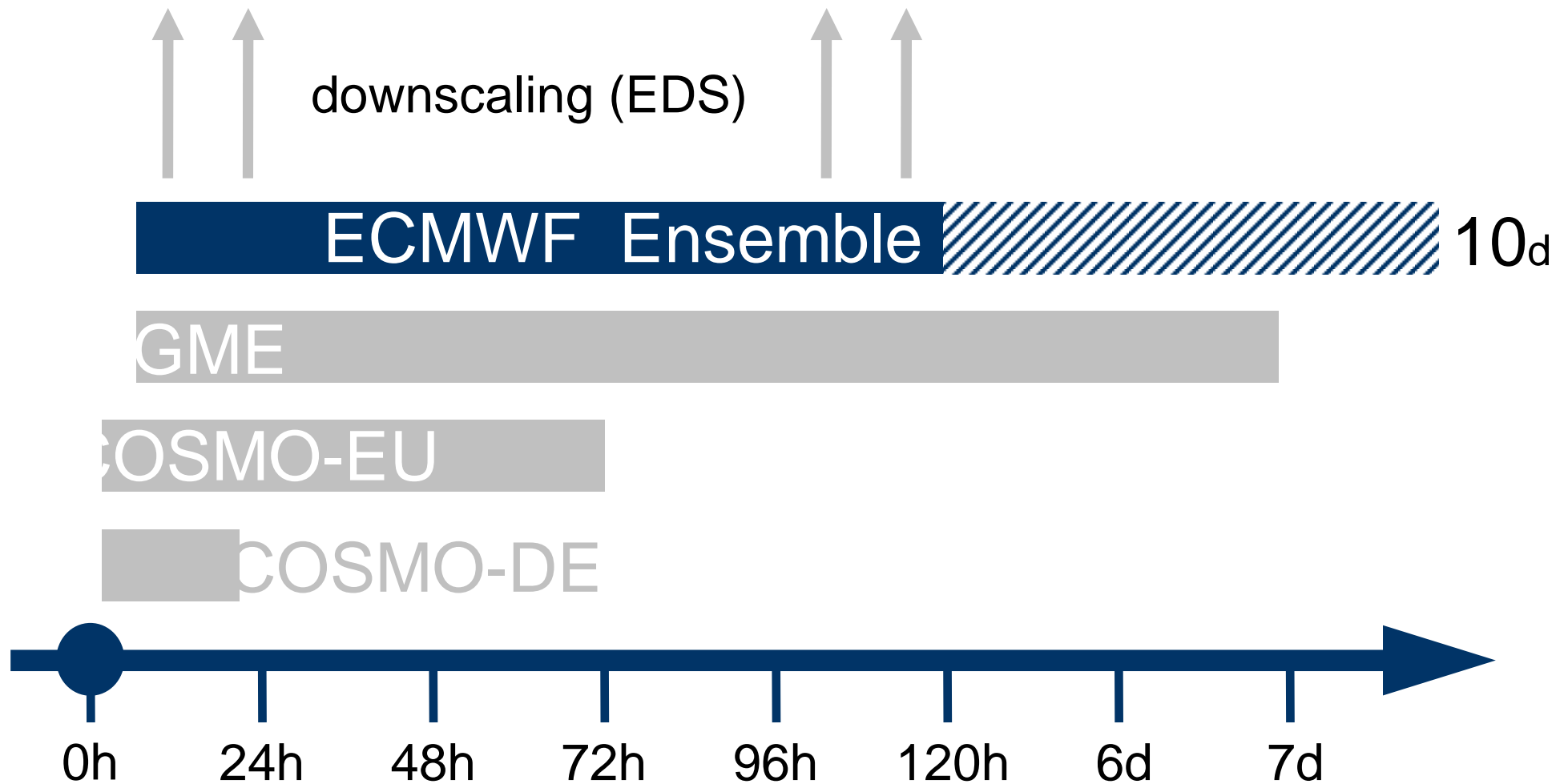
*Matrizenmultiplikation - numerisch **sehr** einfach*

*Vorteil: Lange Simulationen, große Ensembles*

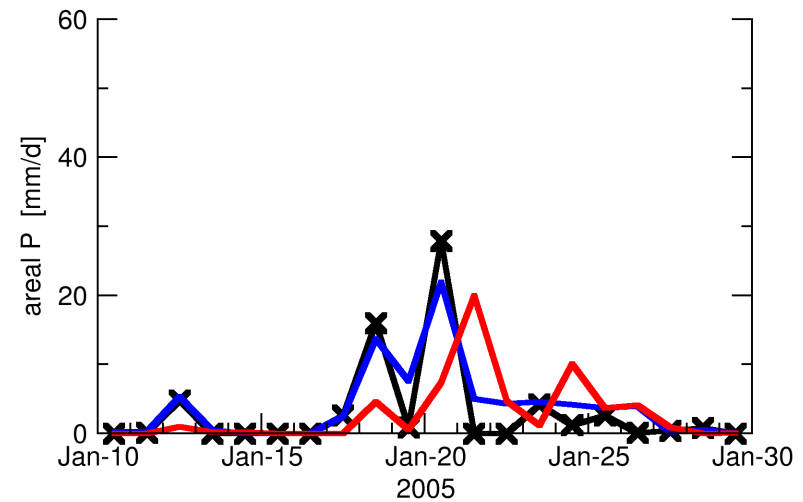
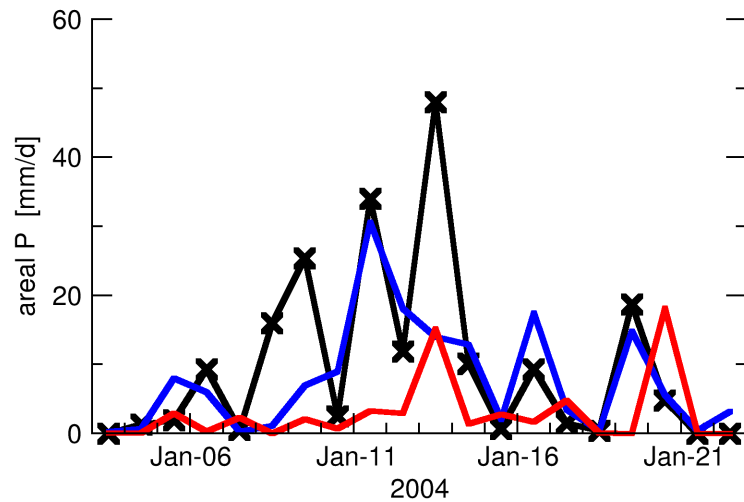
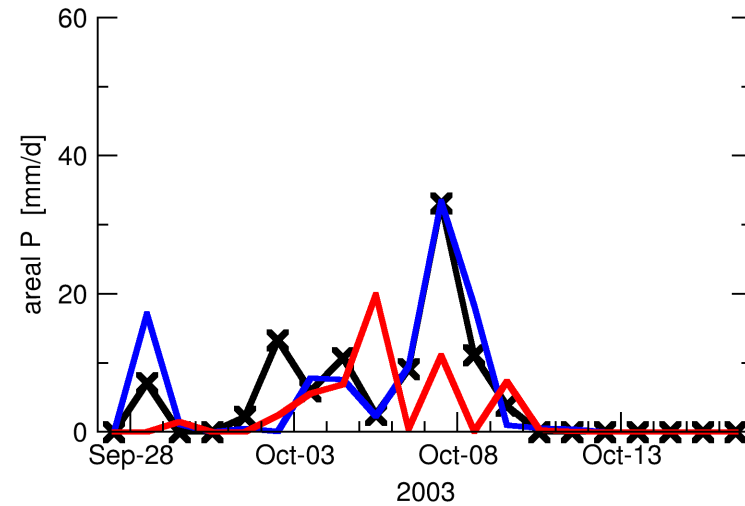
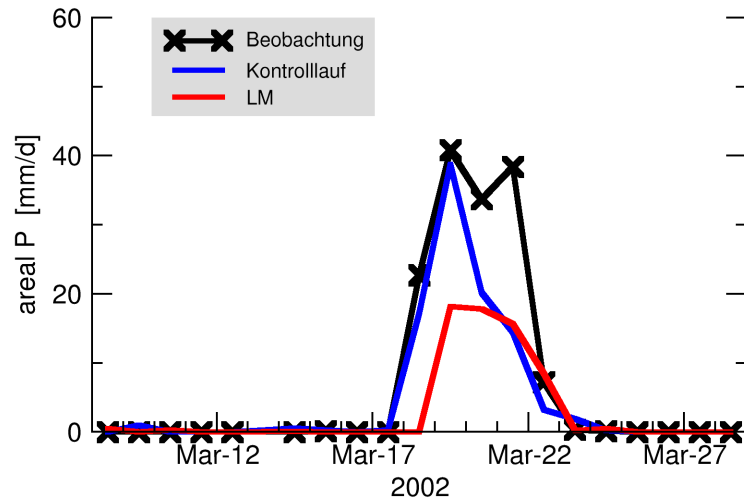
# EPS → EDS



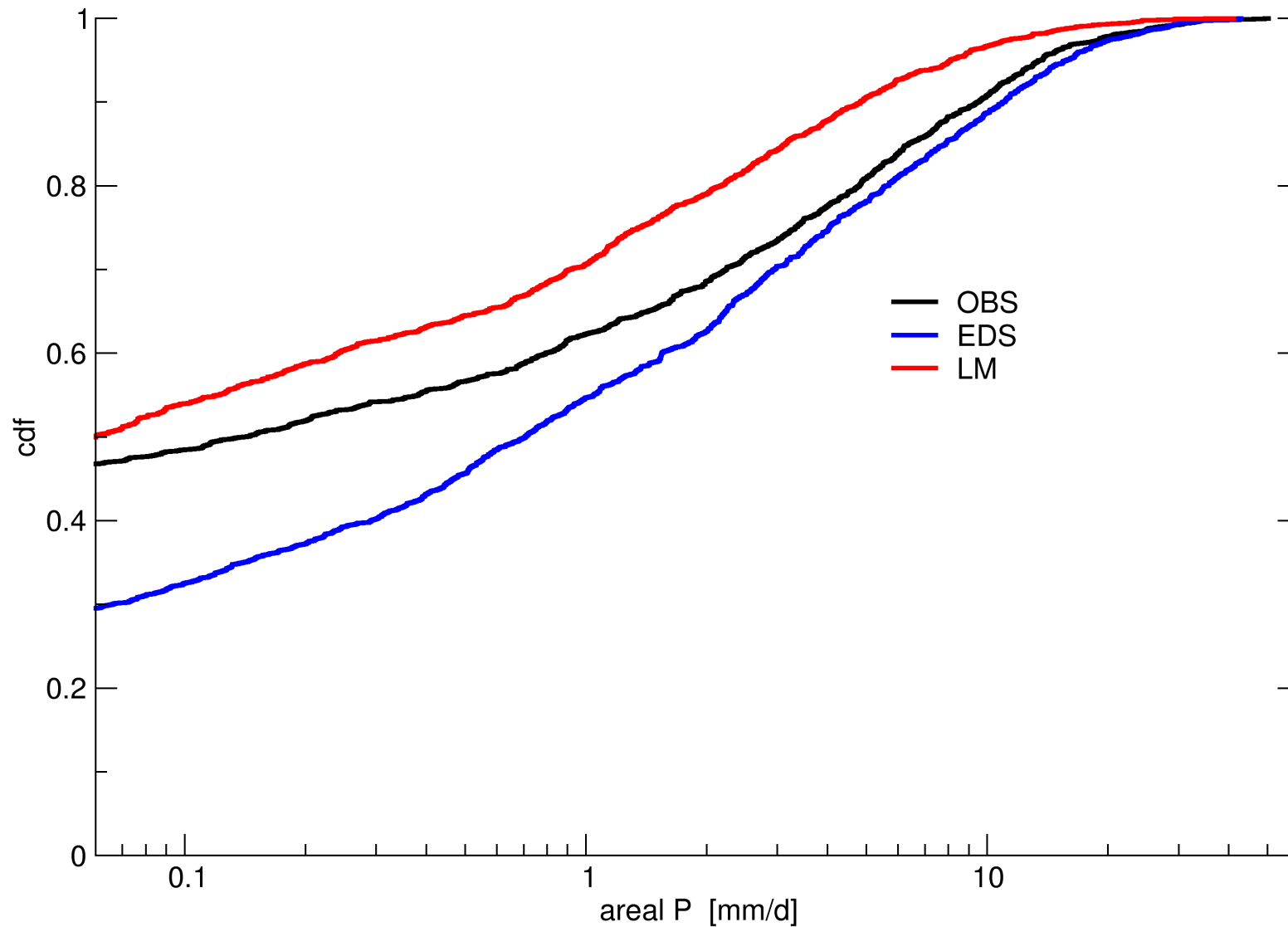
# 51 Stationsvorhersagen für N & T



# Vorhersagen Gebietsniederschlag Alb, +48h



## LM Variabilität zu gering



# Gebietsniederschlag, +48h, 2002 - 2006

$$Q_{95} (Obs) = 14.6 \text{ mm/d}$$

	<b>EDS</b> $\leq Q_{95}$	<b>EDS</b> $> Q_{95}$	
OBS $\leq Q_{95}$	1319	53	1372
OBS $> Q_{95}$	33	26	59
	1352	79	1431

	<b>LM</b> $\leq Q_{95}$	<b>LM</b> $> Q_{95}$	
OBS $\leq Q_{95}$	1351	21	1372
OBS $> Q_{95}$	53	6	59
	1404	27	1431



# Gebietsniederschlag, +48h, 2002 - 2006

$$Q_{99} (Obs) = 26 \text{ mm/d}$$

	<b>EDS</b> $\leq Q_{99}$	<b>EDS</b> $> Q_{99}$	
OBS $\leq Q_{99}$	1405	10	1415
OBS $> Q_{99}$	11	5	16
	1416	15	1431

	<b>LM</b> $\leq Q_{99}$	<b>LM</b> $> Q_{99}$	
OBS $\leq Q_{99}$	1411	4	1415
OBS $> Q_{99}$	16	0	16
	1427	4	1431

## Gilbert skill score (GSS) (syn.: Equitable Threat Score)

	$F = 0$	$F = 1$
$O = 0$	$d$	$b$
$O = 1$	$c$	$a$

$\frac{a}{a+b+c}$  = Treffer pro beob. **oder** vorh. Ereignis

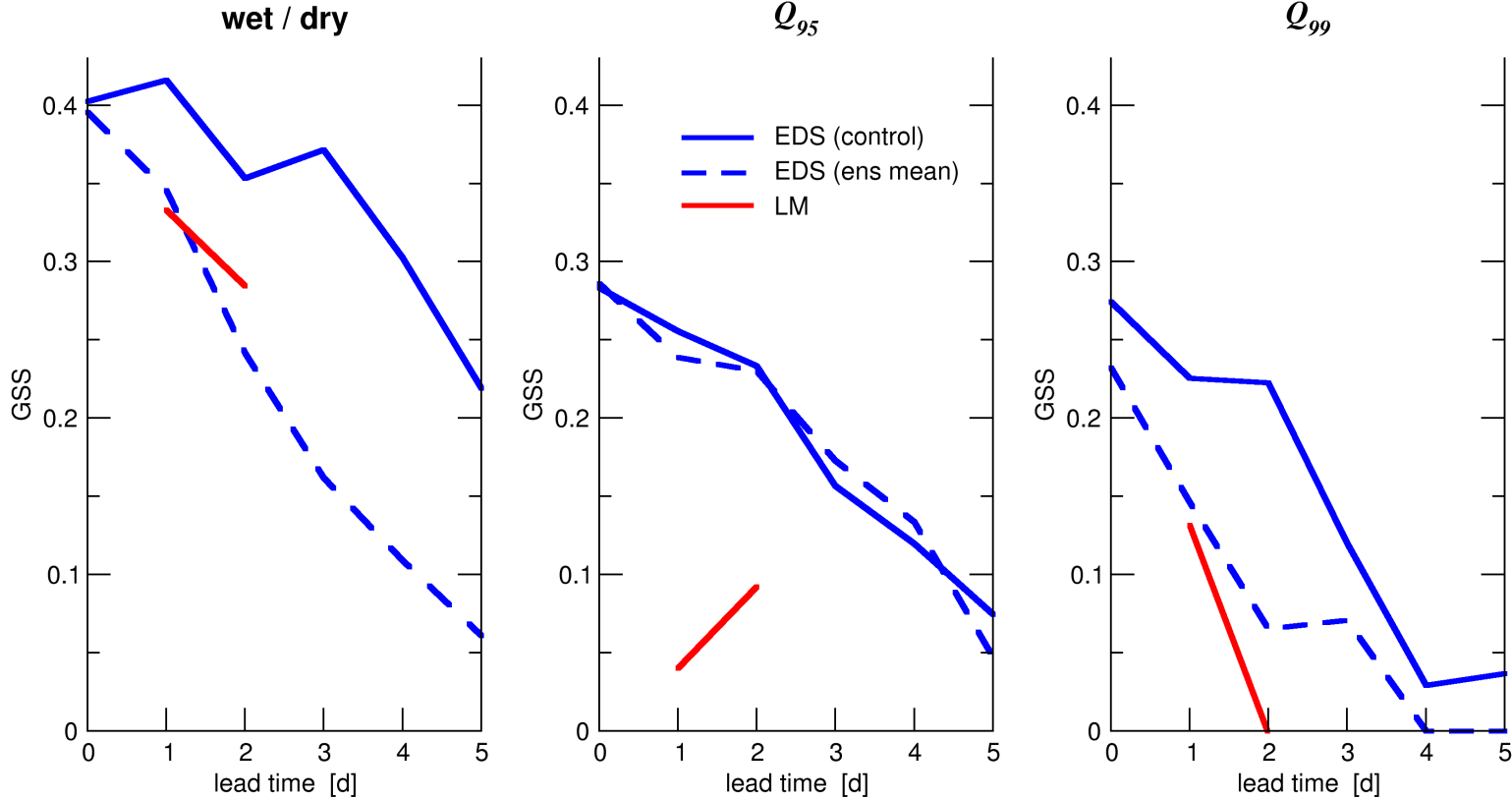
$a \mapsto a - a_R$ : Zufallskorrektur

$$\text{GSS} = \frac{a - a_R}{a - a_R + b + c}$$

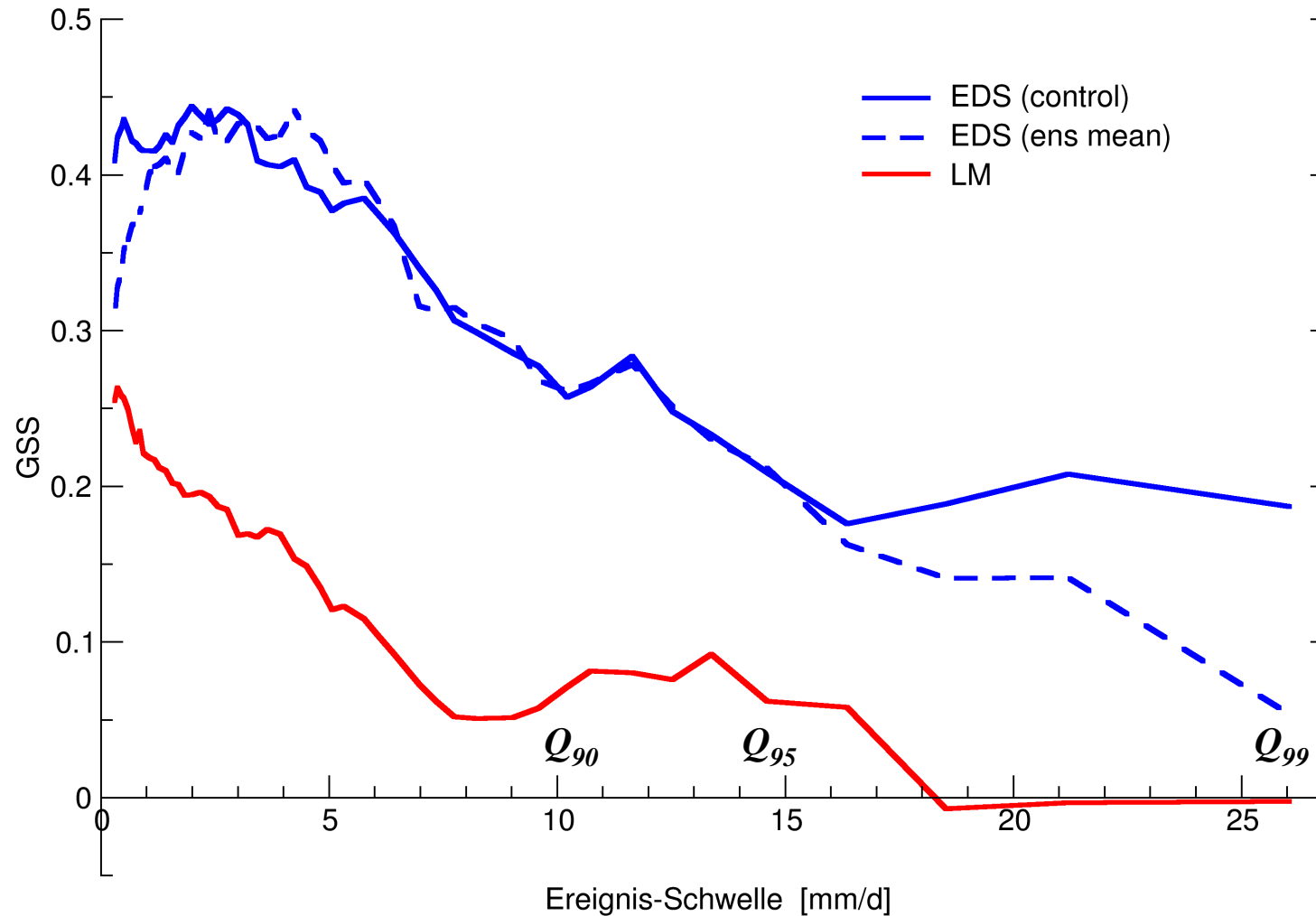
## GSS +48h

	<b>EDS</b>	<b>LM</b>
$Q_{95}$	0.21	0.06
$Q_{99}$	0.19	0

# skill vs. lead time



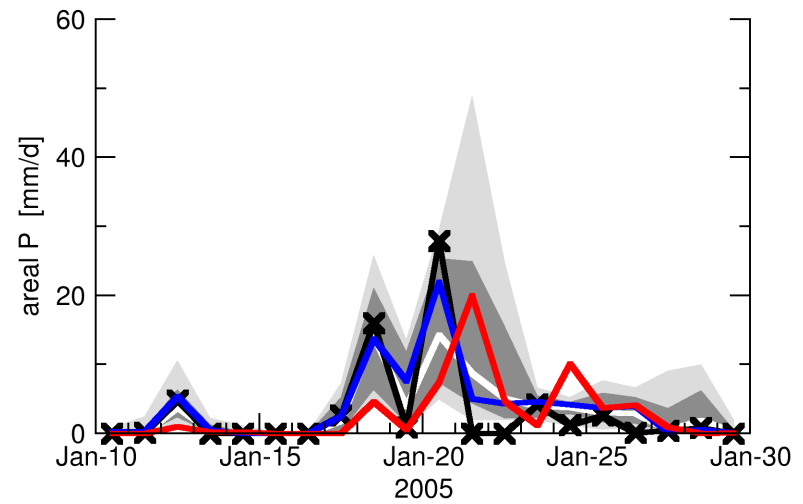
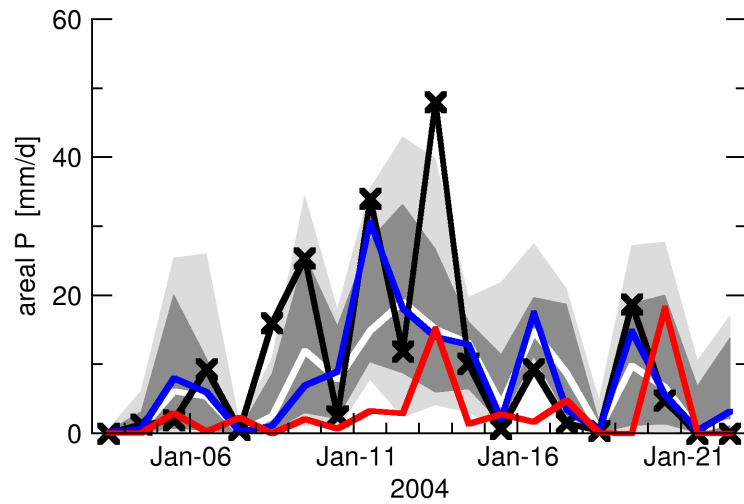
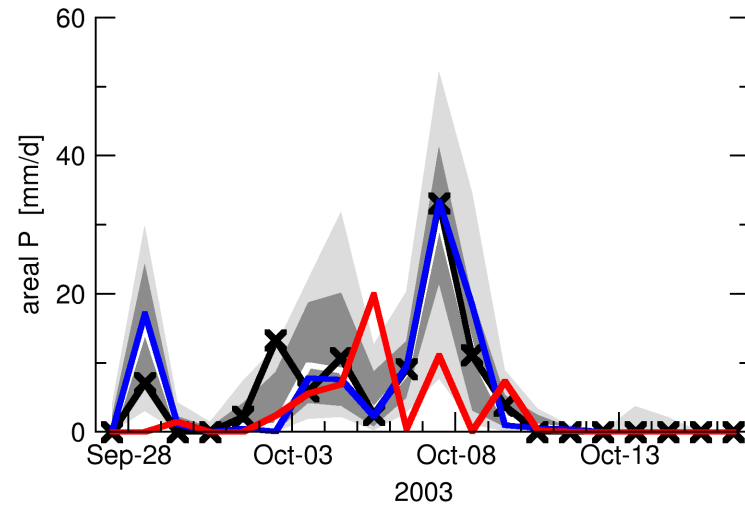
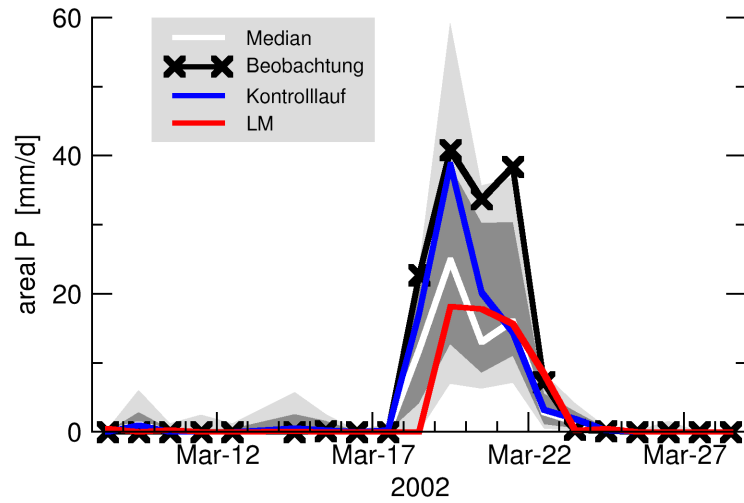
## skill vs. Ereignis-Schwelle (Seltenheit), +48h



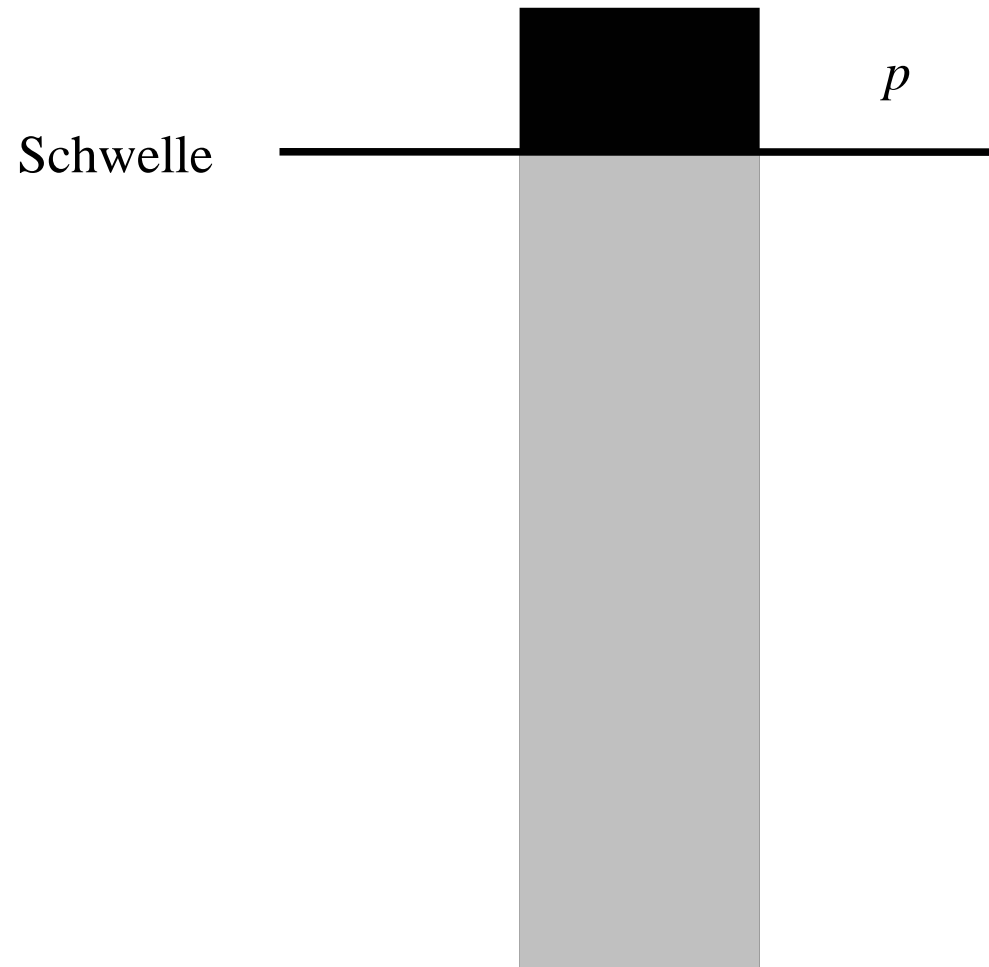
## Zusammenfassung deterministisch

- ECMWF/EDS besser als GME/LM für  $\leq +48\text{h}$  (vorläufig!)
  - vergleiche EFAS
- control besser als ensemble mean. Warum?
- EDS skill (GSS) bis +120h

# +48h Vorhersagen



**ensemble** → **Wahrscheinlichkeit**





# Globale vs. lokale ensembles

## global:

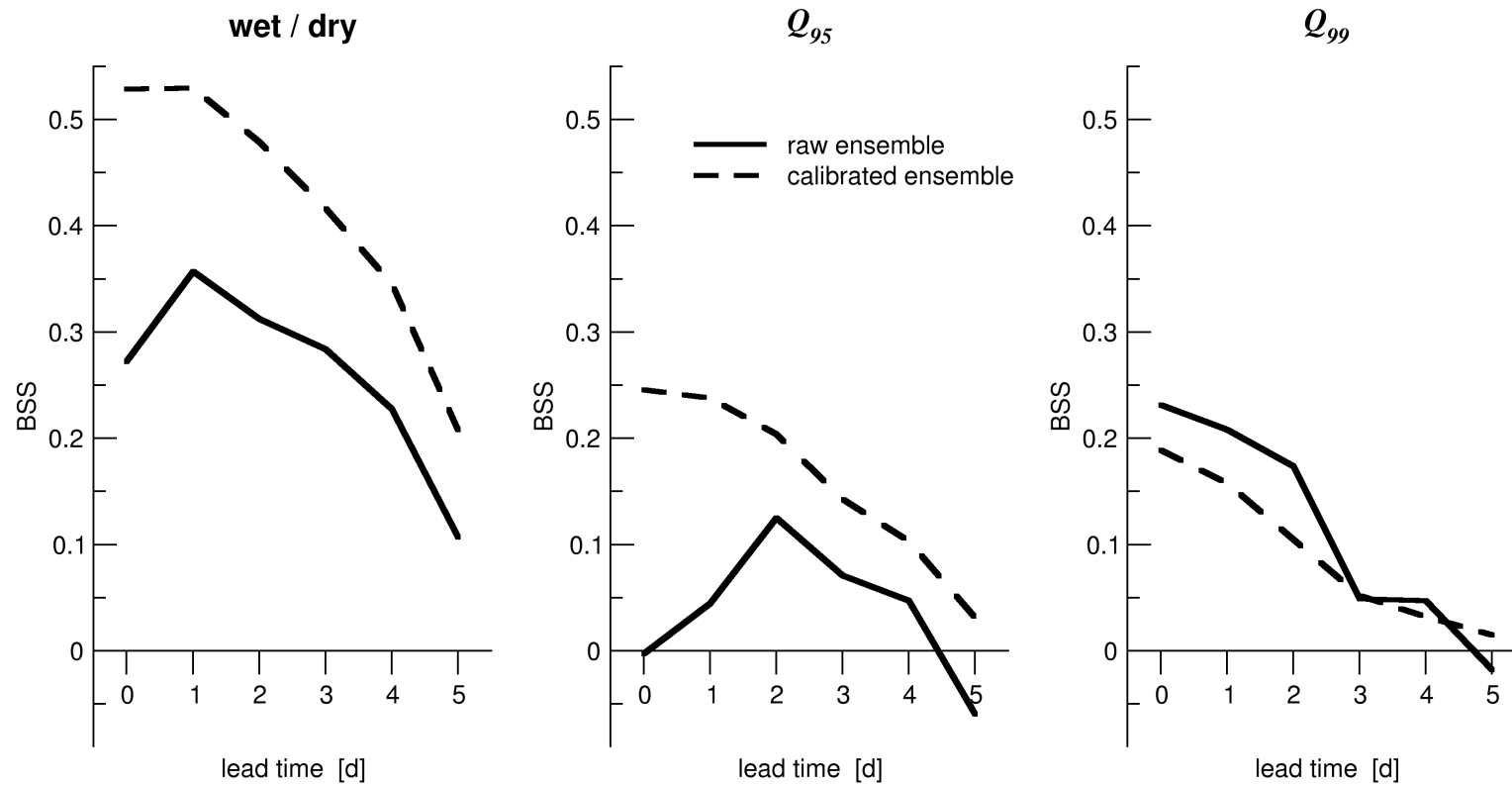
Ensemble **Breite** als Maß für die **Unsicherheit** des Ensemble-Mittels

## lokal:

- Nicht a priori gültig durch überlagerten downscaling Fehler
  - direkte Wahrsch. Vorhersagen nicht "reliable"
- Ausweg: **Kalibrierung** des Ensembles

# Ensemble Kalibrierung

## Brier skill score (BSS) für Alb



## cost-loss Modell

Vorhersage

	<b>EDS <math>\leq Q</math></b>	<b>EDS <math>&gt; Q</math></b>	
OBS $\leq Q$	$d$	$b$	
OBS $> Q$	$c$	$a$	

Kosten

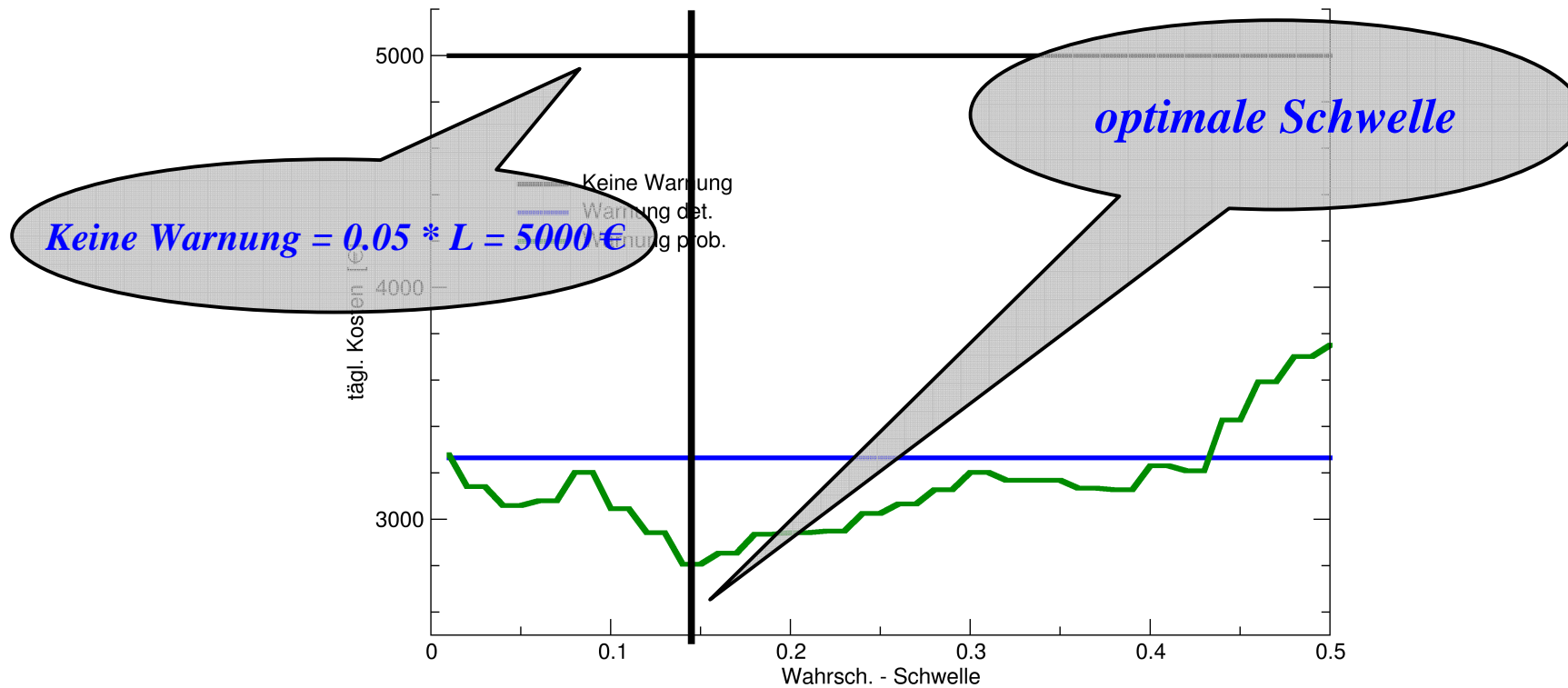
	<b>EDS <math>\leq Q</math></b>	<b>EDS <math>&gt; Q</math></b>	
OBS $\leq Q$	$0$	$C$	
OBS $> Q$	$L$	$C$	

**tägl. Kosten:**

$$A = a \cdot C + b \cdot C + c \cdot L$$

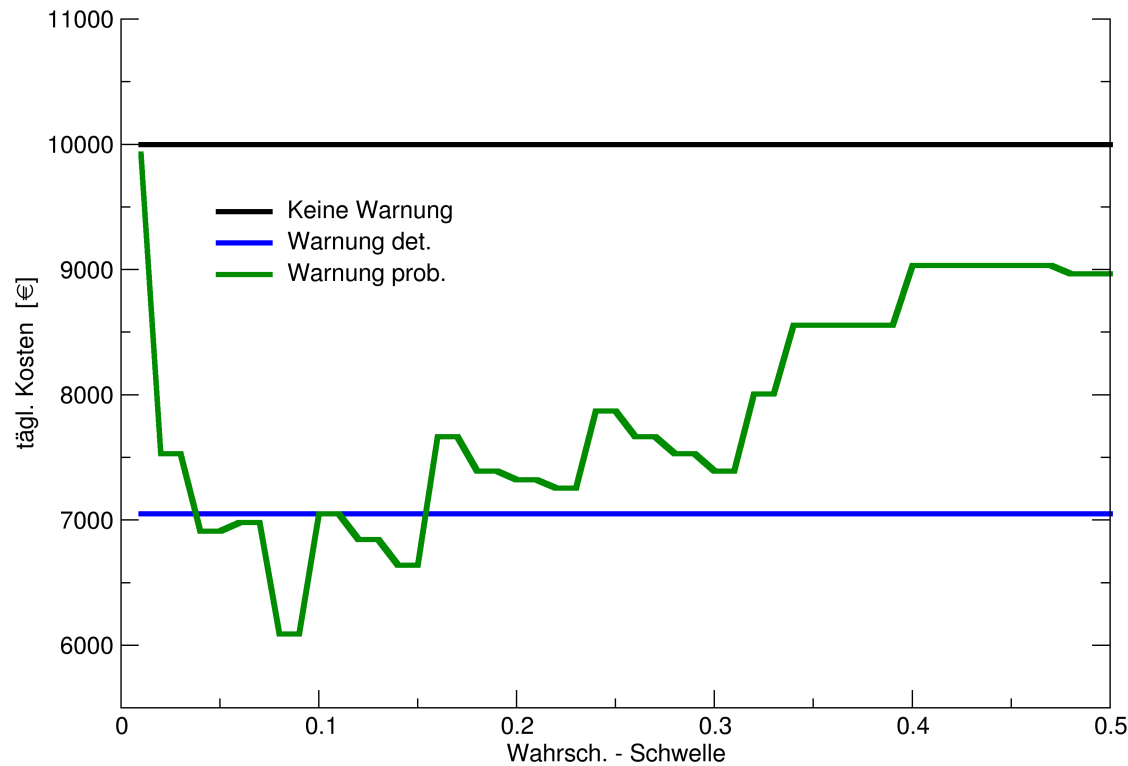
## Beispiel: tägl. Kosten, $Q_{95}$ det. vs. prob.

- Kosten für  $Q_{95}$  Schutzmaßnahmen:  $C = 10000 \text{ €}$
- Verlust bei  $Q_{95}$  ohne Maßnahmen:  $L = 100000 \text{ €}$



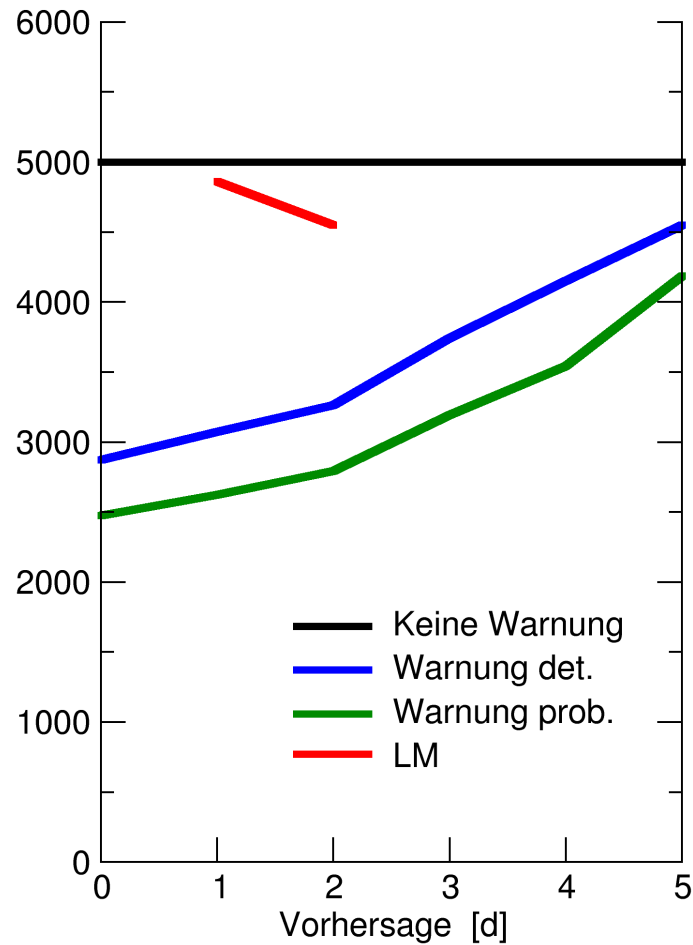
## Beispiel: tägl. Kosten, $Q_{99}$ det. vs. prob.

- Kosten für  $Q_{99}$  Schutzmaßnahmen:  $C = 0.1$  Mio €
- Verlust bei  $Q_{99}$  ohne Maßnahmen:  $L = 1$  Mio €

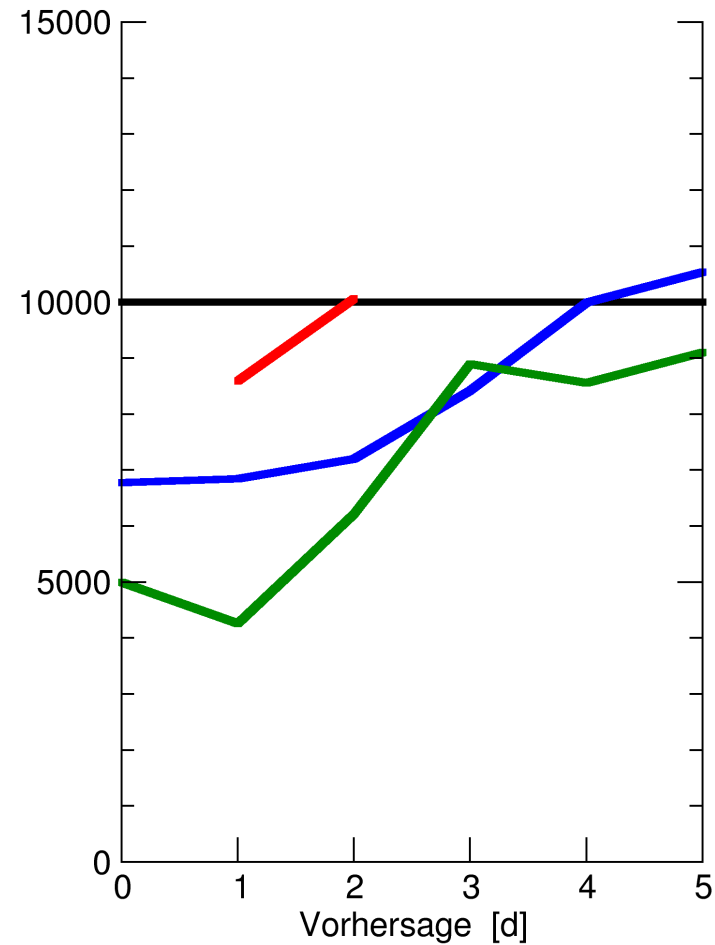


# Mittlere tägl. Kosten ( $C/L = 0.1$ )

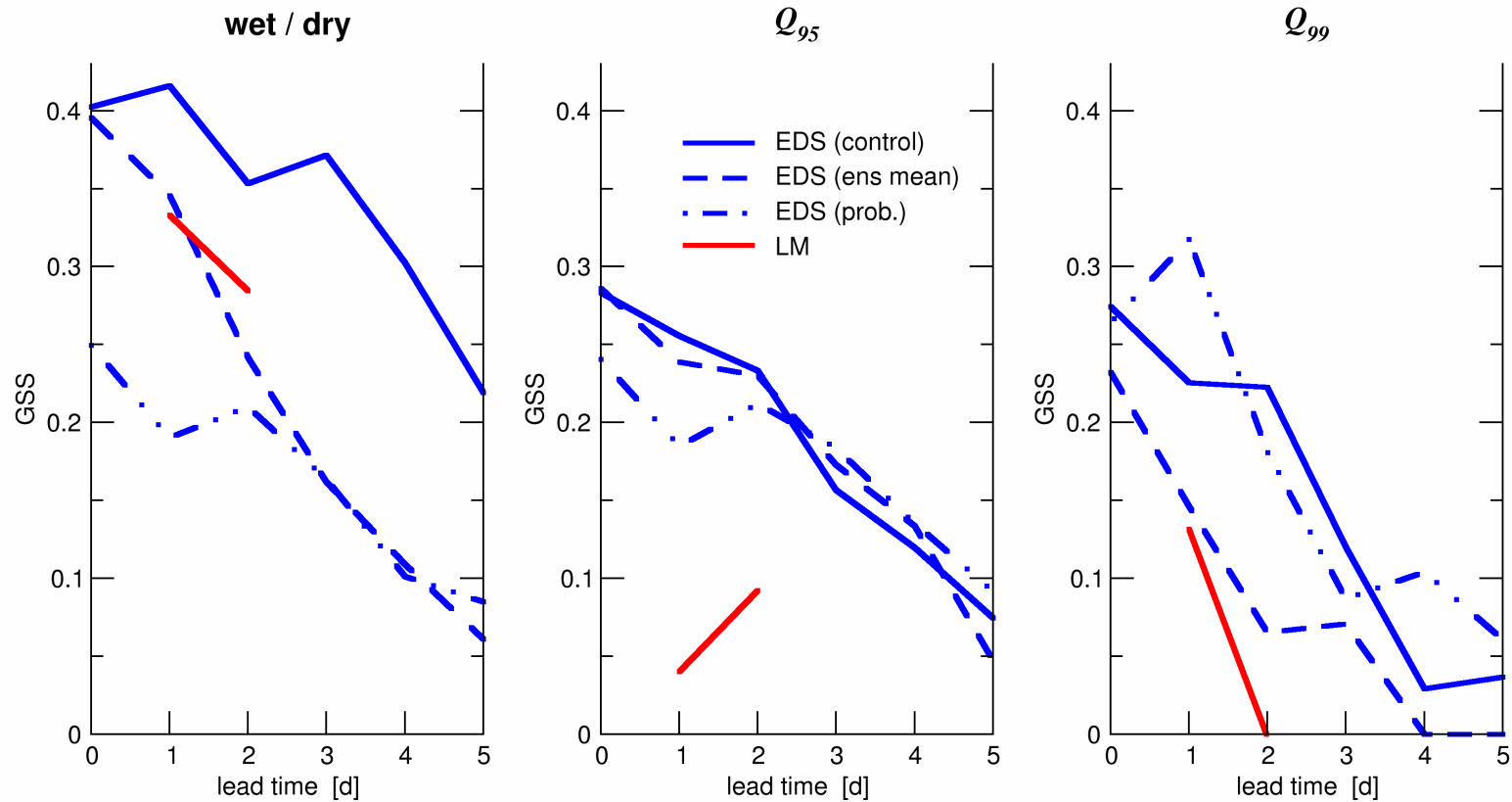
$Q_{95}, L=0.1M€$



$Q_{99}, L=1M€$

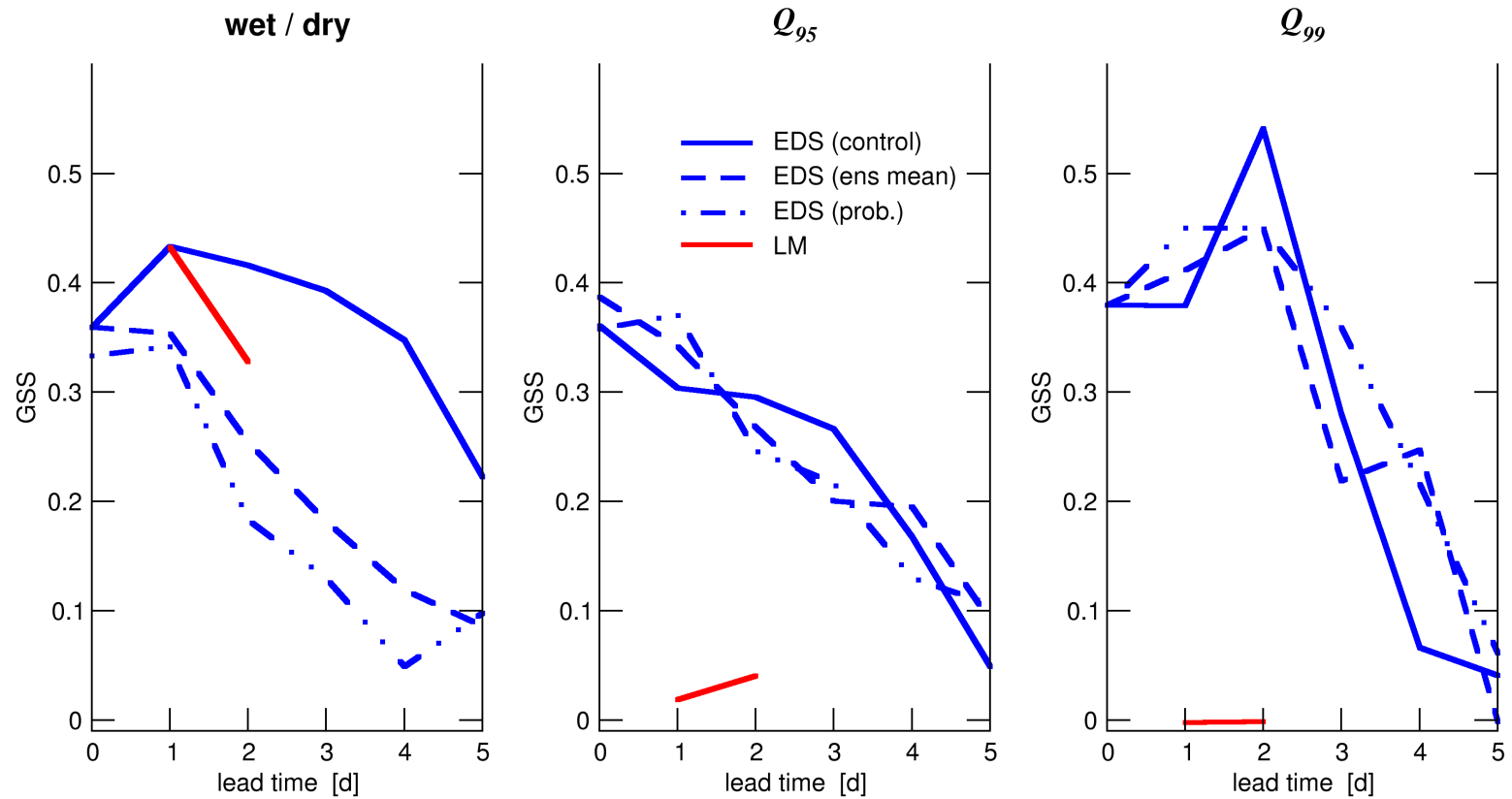


# skill vs. lead time



# skill vs. lead time

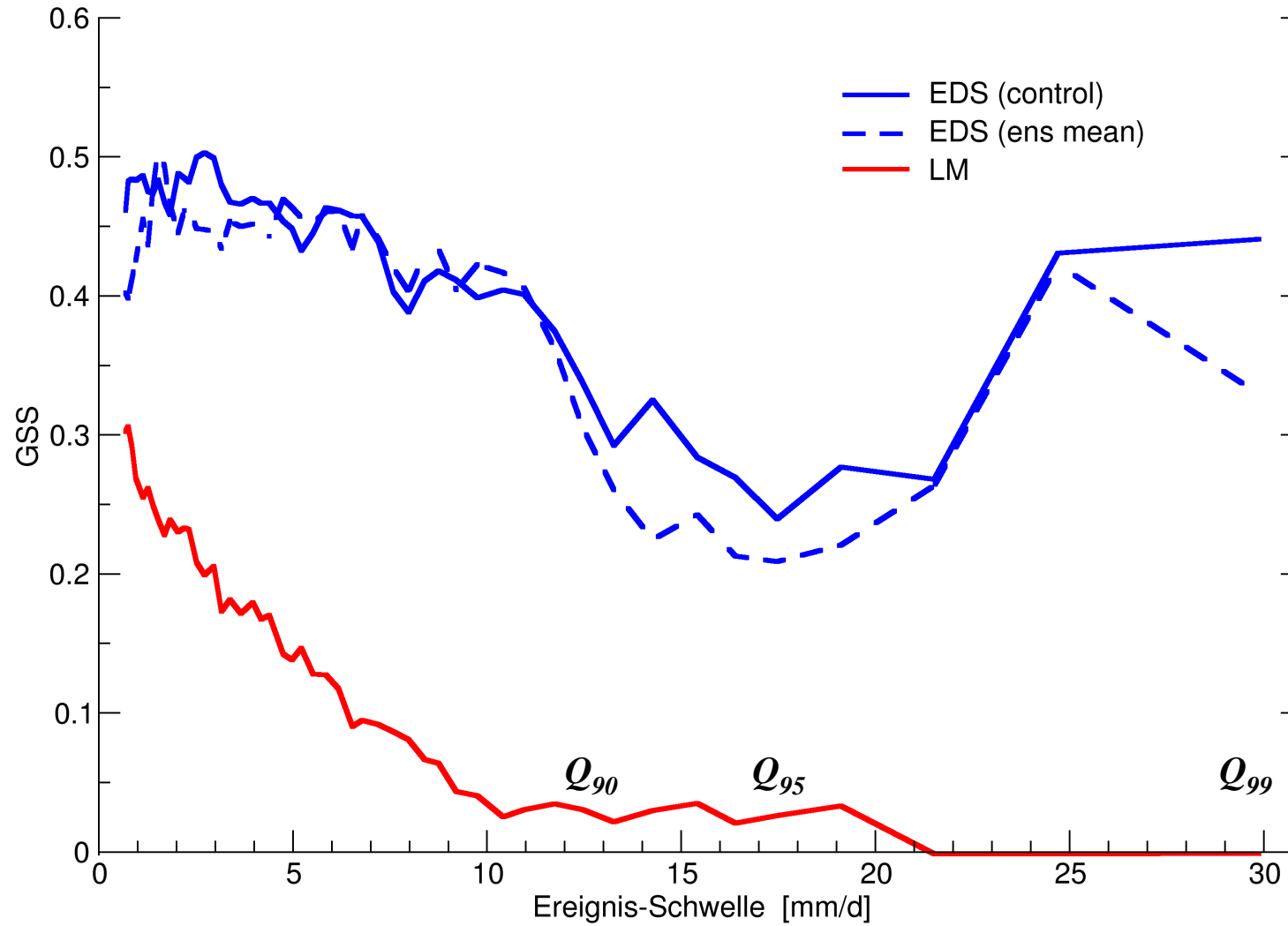
## Obere Donau





# skill vs. Ereignis-Schwelle (Seltenheit), +48h

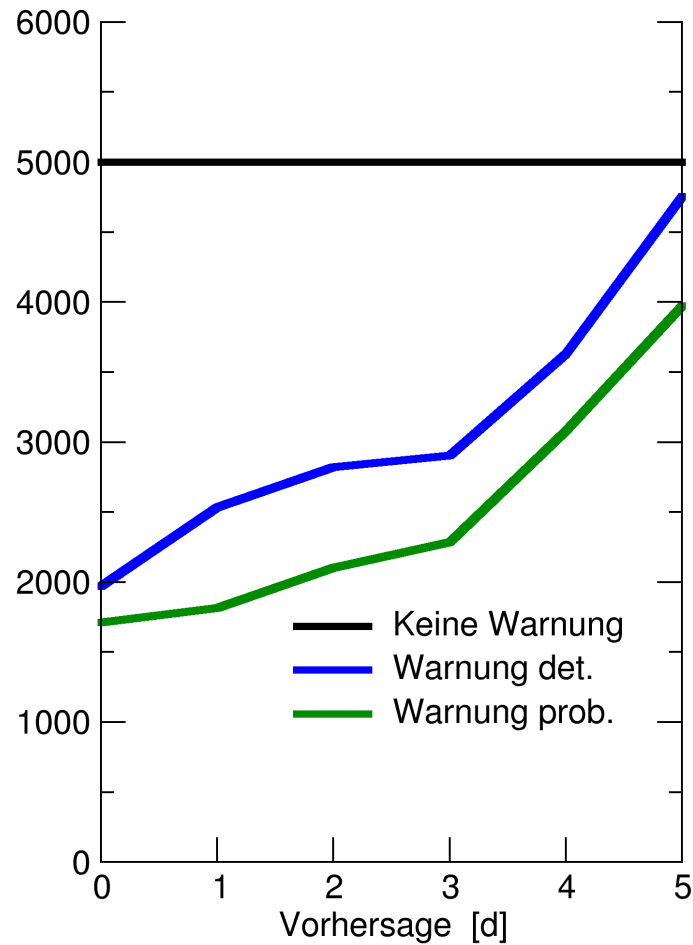
## Obere Donau



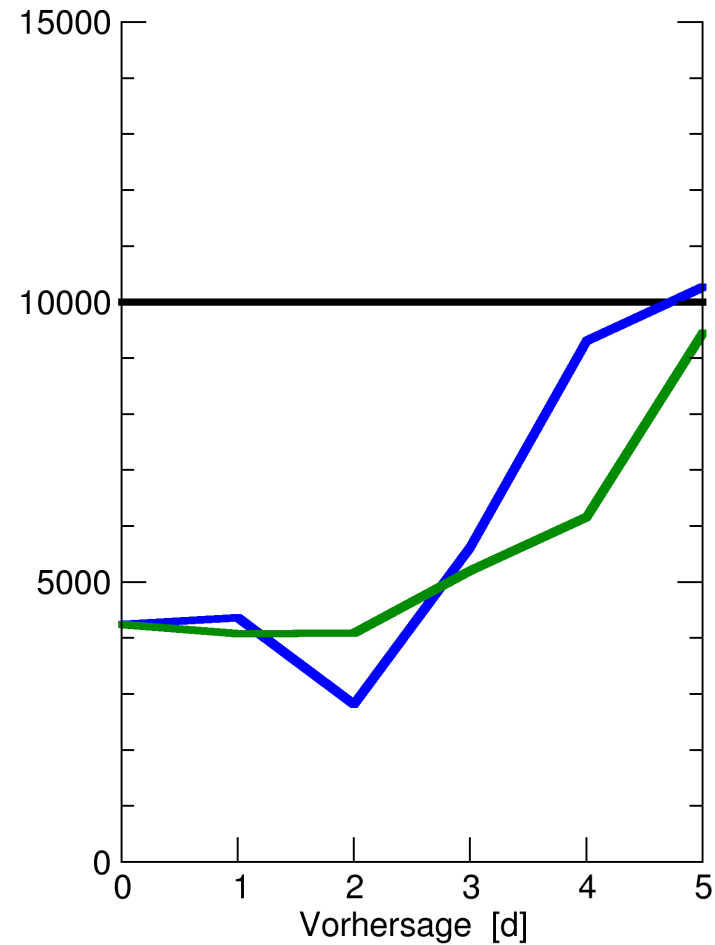
# Mittlere tägl. Kosten, ( $C/L = 0.1$ )

## Obere Donau

$Q_{95}, L=0.1M€$



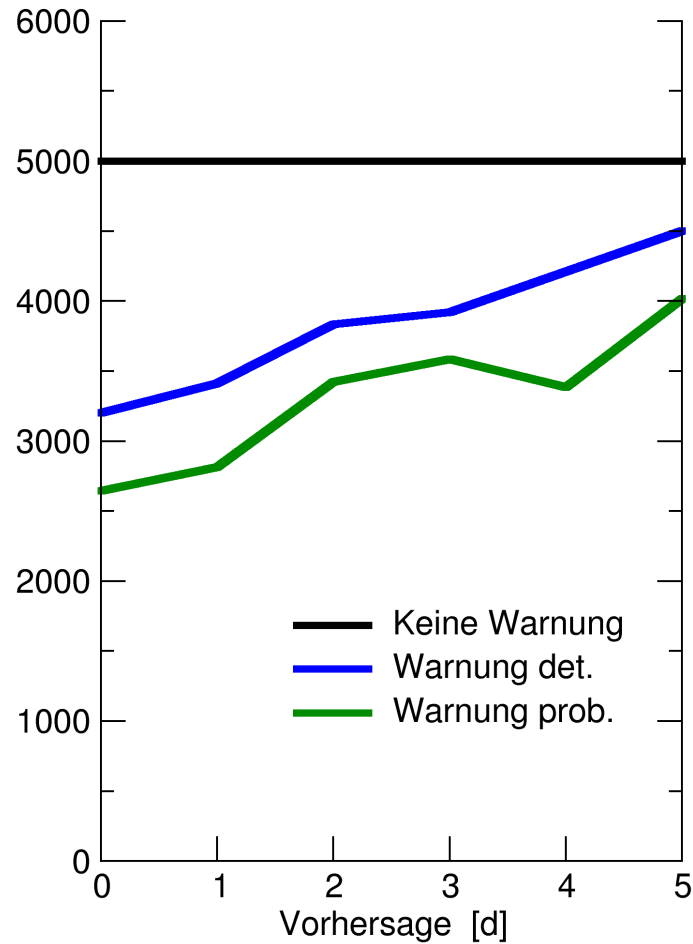
$Q_{99}, L=1M€$



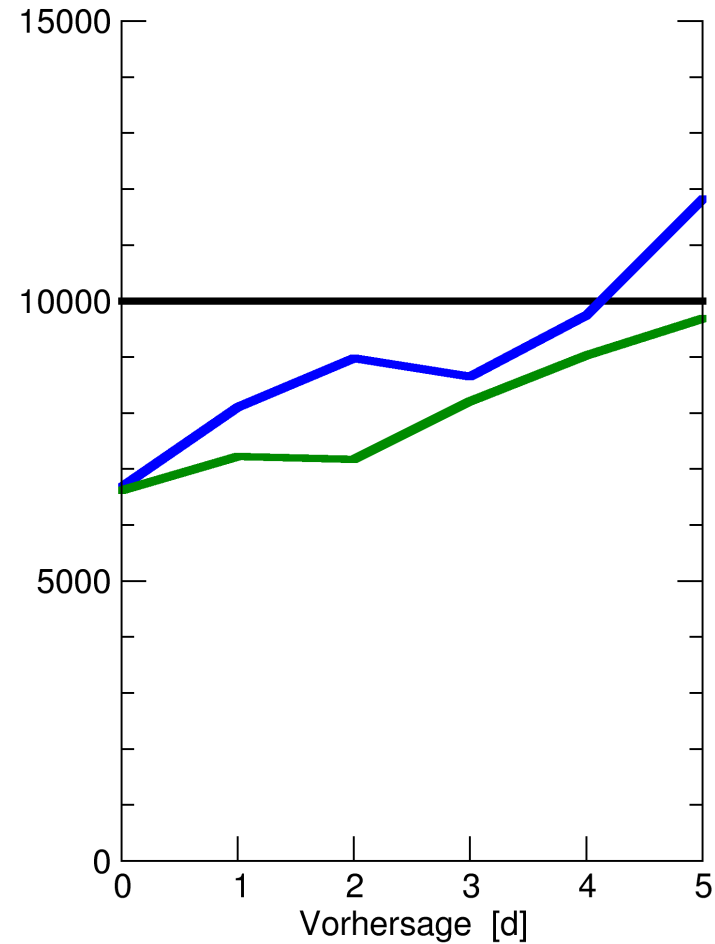
# Mittlere tägl. Kosten, ( $C/L = 0.1$ )

## Weißeritz

$Q_{95}, L=0.1M€$



$Q_{99}, L=1M€$

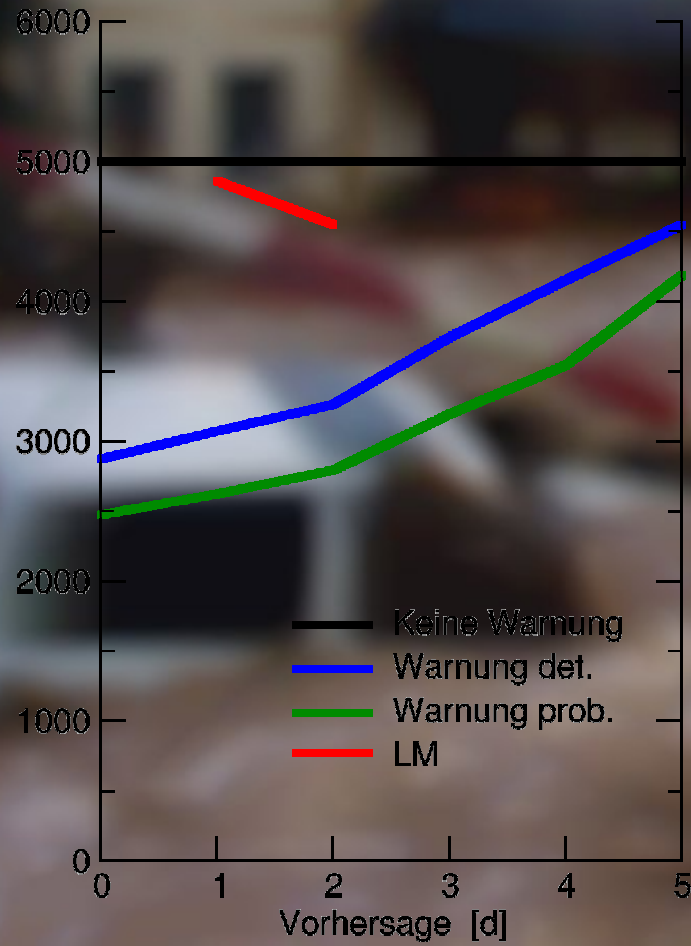


## Zusammenfassung & Ausblick

- Empirisches downscaling (EDS) besser als dynamisches (LM) (**vorläufig!**)
  - zu geringe LM Variabilität
- EDS ensemble mean schlecht
  - Lokale Ensemble Breite  $\neq$  Modellfehler?
  - Ensemble Kalibrierung
- VHS aus Ensemble am besten, GSS skill bis +5d
- Ökonomischer Wert der prob. VHS nutzerabhängig (cost/loss ratio)
  - im hydr. Kontext (C/L~0.1) **nützlich bis +5d**
- Donau ähnlich, Weißeritz etwas schlechter (kontinentaler Einfluß?)
- Hydrologie?
- Vergleiche OPAQUE mit EFAS und COSMO-LEPS!

# Ende

$Q_{95}, L=0.1M\text{€}$



$Q_{99}, L=1M\text{€}$

